The derivation of the steady state equation by Bengt-Olof Drugge 070522

Constant momentum

$$\mathbf{w} \cdot \mathbf{v}_1 \cdot \mathbf{R} = \mathbf{w} \cdot \mathbf{v}_2 \cdot \mathbf{R}_0$$

 $\mathbf{w} \cdot \mathbf{R}^2 = \frac{2 \cdot \pi \cdot (\mathbf{R}_0)^2}{T}$

$$\omega = \frac{2 \cdot \pi \cdot \left(R_{o}\right)^{2}}{T \cdot R^{2}}$$

T = Rotation time of the object Ro = Radii of the object mo= mass of the object

Cetripethalforce

$$F = m \cdot \omega^2 \cdot R$$

$$F = \frac{m \cdot 4 \cdot \pi^2 \cdot (R_o)^4}{T^2 \cdot R^3}$$

Gravitylaw

$$F = \frac{G \cdot m \cdot m_o}{R^2}$$

The steady state equation

$$F(R) = \frac{m \cdot 4 \cdot \pi^2 \cdot (R_o)^4}{T^2 \cdot R^3} - \frac{G \cdot m \cdot m_o}{R^2}$$
$$R_{ss} = \frac{4 \cdot \pi^2 \cdot (R_o)^4}{G \cdot m_o \cdot T^2}$$

The Steady State Radii